### Temporal logics for multi-agent systems

Nicolas Markey LSV – ENS Cachan

(based on joint works with Thomas Brihaye, Arnaud Da Costa-Lopes, François Laroussinie)



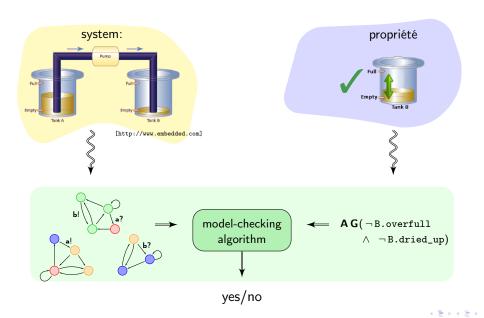


« Formalisation des Activités Concurrentes »

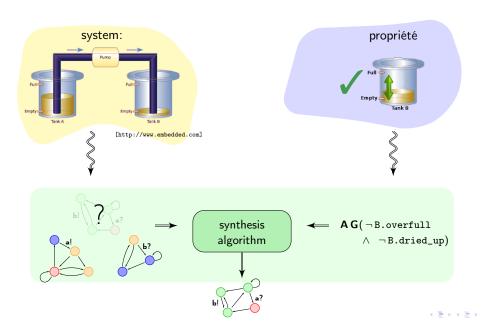
Toulouse, 16 April 2014



# Model checking and synthesis



# Model checking and synthesis



## Outline of the presentation

- Introduction
- Basics of CTL and ATL
  - expressing properties of reactive systems
  - efficient verification algorithms
- 3 Temporal logics for multi-agent systems
  - specifying properties of complex interacting systems
  - expressive power of ATL<sub>sc</sub>
  - translation into Quantified CTL (QCTL)
  - algorithms for ATL<sub>sc</sub>
- 4 Conclusions and future works



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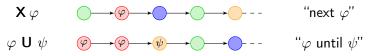


• atomic propositions:  $\bigcirc$ ,  $\bigcirc$ , ...



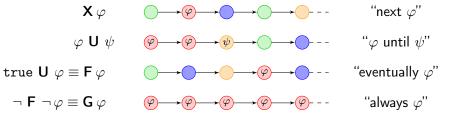
- atomic propositions: O, O, ...
- boolean combinators:  $\neg \varphi$ ,  $\varphi \lor \psi$ ,  $\varphi \land \psi$ , ...

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- temporal modalities:



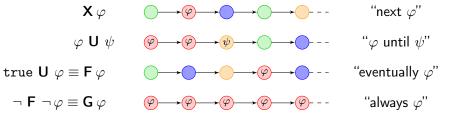


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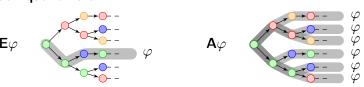




- atomic propositions:  $\bigcirc$ ,  $\bigcirc$ , ...
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• path quantifiers:

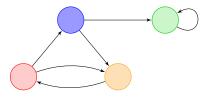


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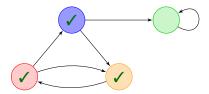






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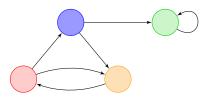




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 $\mathsf{EG}(\neg \bigcirc \land \mathsf{EF} \bigcirc)$ 

there is a path along which is always reachable, but never reached

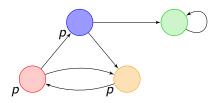




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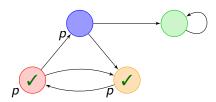




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Theorem ([CE81,QS82])

CTL model checking is PTIME-complete.

[CE81] Clarke, Emerson. Design and Synthesis of Synchronization Skeletons using Branching-Time Temporal Logic. LOP'81.

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#### Theorem ([KVW94])



CTL model checking on product structures is PSPACE-complete.

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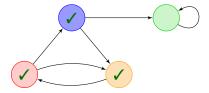


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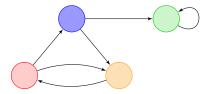
**EGF** there is a path visiting infinitely many times





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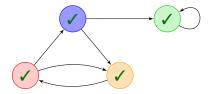
 $\mathsf{A}(\mathsf{G}\,\mathsf{F} \bigcirc \Rightarrow \mathsf{G}(\,\neg\,\bigcirc)) \qquad \text{any path that visits} \bigcirc \text{infinitely many times,}$  never visits  $\bigcirc$ 





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#### Theorem ([EH86,KVW94])

CTL\* model checking is PSPACE-complete.

### Theorem ([KVW94])

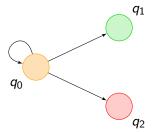
CTL\* model checking on product structures is PSPACE-complete.

[EH86] Emerson, Halpern. "Sometimes" and "Not Never" Revisited: On Branching versus Linear Time Temporal Logic. J.ACM, 1986. [KVW94] Kupferman, Vardi, Wolper. An automata-theoretic approach to branching-time model checking. CAV'94.

#### Concurrent games

A concurrent game is made of

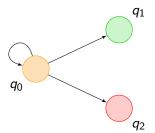
• a transition system;



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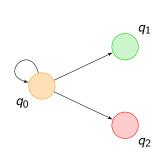
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A concurrent game is made of

- a transition system;
- a set of agents (or players);
- a table indicating the transition to be taken given the actions of the players.



		player 1		
				20
player 2		90	$q_2$	$q_1$
		$q_1$	90	<b>q</b> 2
	8	<b>q</b> <sub>2</sub>	$q_1$	90

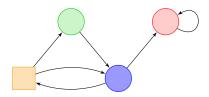
#### Concurrent games

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- a table indicating the transition to be taken given the actions of the players.

#### Turn-based games

A turn-based game is a game where only one agent plays at a time.



### Strategies

A strategy for a given player is a function telling what to play depending on what has happened previously.

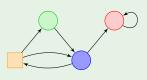


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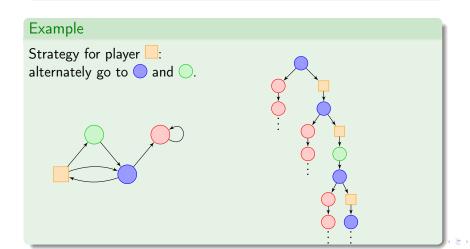
#### Example

Strategy for player : alternately go to and .



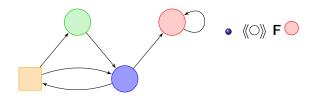
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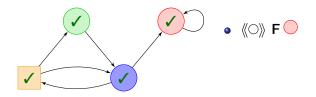


### ATL extends CTL with strategy quantifiers

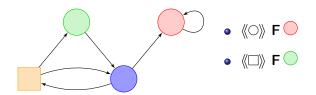
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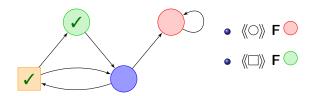
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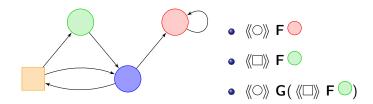
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# Temporal logics for games: ATL

## ATL extends CTL with strategy quantifiers

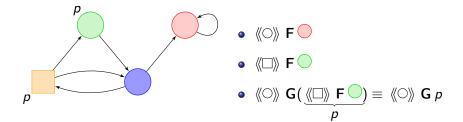
 $\langle\!\langle A \rangle\!\rangle \varphi$  expresses that A has a strategy to enforce  $\varphi$ .



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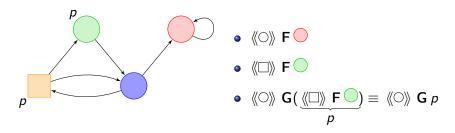
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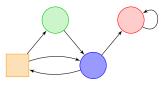
## Theorem ([AHK02])

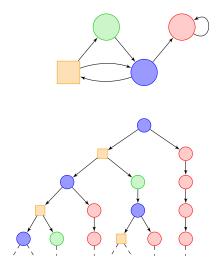
Model checking ATL is PTIME-complete. Model checking ATL\* is 2-EXPTIME-complete.

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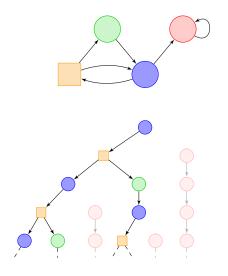






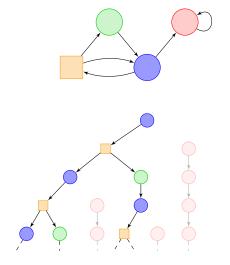
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[BDLM09]



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- consider the following strategy of Player ○: "always go to ";
- in the remaining tree, Player can always enforce a visit to .

# ATL with strategy contexts

### Definition

ATL<sub>sc</sub> has two new strategy quantifiers:  $\langle A \rangle \varphi$  and  $\langle A - \rangle \varphi$ .

•  $\langle A \rangle$  is similar to  $\langle A \rangle$  but assigns the corresponding strategy to A for evaluating  $\varphi$ ;



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- $\langle -A \rangle$  drops the assigned strategies for A.
- [A] is dual to  $\langle A \rangle$ :

$$[A]\varphi \equiv \neg \langle A \rangle \neg \varphi$$

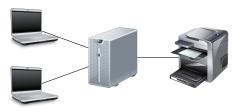
 $[A] \varphi$  which states that any strategy for A has an outcome along which  $\varphi$  holds.



## What ATL<sub>sc</sub> can express

• Client-server interactions for accessing a shared resource:

$$\langle \mathsf{Server} \rangle \; \mathbf{G} \left[ \begin{array}{c} \bigwedge\limits_{c \in \mathsf{Clients}} \langle c \cdot \rangle \; \mathbf{F} \, \mathsf{access}_c \\ \wedge \\ \neg \bigwedge\limits_{c \neq c'} \mathsf{access}_c \; \wedge \; \mathsf{access}_{c'} \end{array} \right]$$





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Existence of Nash equilibria:

$$\langle A_1, ..., A_n \rangle \bigwedge_i (\langle A_i \rangle \varphi_{A_i} \Rightarrow \varphi_{A_i})$$



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Existence of Nash equilibria:

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Existence of dominating strategy:

$$\langle A \rangle [B] (\neg \varphi \Rightarrow [A] \neg \varphi)$$



### **Theorem**

- ATL<sub>sc</sub> is strictly more expressive than ATL,
- The operator <-A-> does not add expressive power,
- $ATL_{sc}$  is as expressive as  $ATL_{sc}^*$ .



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### Proof

$$\langle\!\langle A \rangle\!\rangle\,\varphi \equiv \,\langle \text{-Agt--} \rangle \,\,\langle \cdot A \cdot \rangle \,\hat{\varphi}$$

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### Proof

 $\langle 1 \rangle$  (  $\langle 2 \rangle$  **X**  $a \land \langle 2 \rangle$  **X** b) is only true in the second game. But ATL cannot distinguish between these two games.



#### **Theorem**

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- The operator  $\langle -A \rangle$  does not add expressive power,
- ATL<sub>sc</sub> is as expressive as ATL<sub>sc</sub>.

### Proof

Replace implicit quantification with explicit one:

$$\langle 1 \rangle \, \varphi \equiv \, \langle 1 \rangle \, \left[ \mathsf{Agt} \setminus \{1\} \right] \, \langle \emptyset \rangle \, \widehat{\varphi}$$

 $\sim$  we can always assume that the context is full.



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- $\langle -A \rangle \varphi$  is then equivalent to  $[A] \langle \emptyset \rangle \varphi$ ;
- $\langle \emptyset \rangle$  can be inserted between two temporal modalities.



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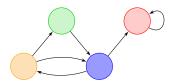
 $\exists p. \ \varphi$  means that there exists a labelling of the model with p under which  $\varphi$  holds.

[ES84] Emerson and Sistla. Deciding Full Branching Time Logic. Information & Control, 1984. [Kup95] Kupferman. Augmenting Branching Temporal Logics with Existential Quantification over Atomic Propositions. CAV, 1995.

[Fre01] French. Decidability of Quantifed Propositional Branching Time Logics. AJCAI, 2001: \* 4 🛢 🕨

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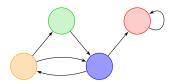
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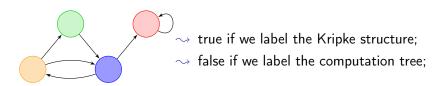
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# Semantics of QCTL

• structure semantics:

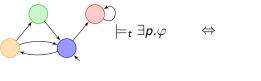


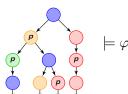
# Semantics of QCTL

• structure semantics:



• tree semantics:







## Expressiveness of QCTL

QCTL can "count":

$$\mathbf{E} \, \mathbf{X}_1 \, \varphi \equiv \mathbf{E} \, \mathbf{X} \, \varphi \, \wedge \, \forall p. \, \left[ \mathbf{E} \, \mathbf{X} (p \, \wedge \, \varphi) \, \Rightarrow \, \mathbf{A} \, \mathbf{X} (\varphi \, \Rightarrow \, p) \right]$$
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QCTL can express (least or greatest) fixpoints:

$$\mu T.\varphi(T) \equiv \exists t. \ [\mathbf{A} \ \mathbf{G}(t \iff \varphi(t)) \land \\ (\forall t.'(\mathbf{A} \ \mathbf{G}(t' \iff \varphi(t')) \Rightarrow \mathbf{A} \ \mathbf{G}(t \Rightarrow t')))]$$

[DLM12] Da Costa, Laroussinie, M. Quantified CTL: expressiveness and model checking.



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#### **Theorem**

QCTL, QCTL\* and MSO are equally expressive (under both semantics).





## QCTL with structure semantics

### **Theorem**

Model checking QCTL for the structure semantics is PSPACE-complete.

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### Proof

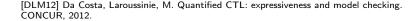
## Membership:

Iteratively

- (nondeterministically) pick a labelling,
- check the subformula.

#### Hardness:

QBF is a special case (without even using temporal modalities).





## QCTL with structure semantics

#### **Theorem**

Model checking QCTL for the structure semantics is PSPACE-complete.

### Proof

### Membership:

Iteratively

- (nondeterministically) pick a labelling,
- check the subformula.

#### Hardness:

QBF is a special case (without even using temporal modalities).

#### **Theorem**

QCTL satisfiability for the structure semantics is undecidable.

[DLM12] Da Costa, Laroussinie, M. Quantified CTL: expressiveness and model checking. CONCUR, 2012.



#### **Theorem**

- Model checking QCTL with k quantifiers in the tree semantics is k-EXPTIME-complete.
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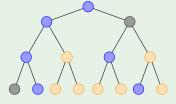
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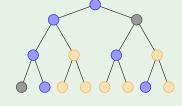
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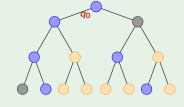
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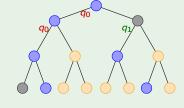
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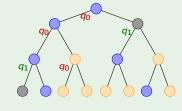
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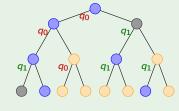
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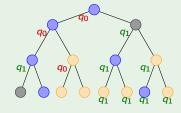
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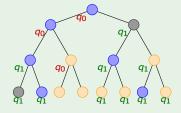
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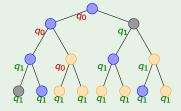
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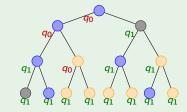
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This automaton corresponds to **E** U







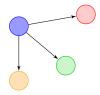
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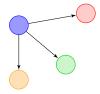
- polynomial-size automata for CTL;
- quantification is handled by projection, which first requires removing alternation (exponential blowup);
- an automaton equivalent to a QCTL formula can be built inductively;
- emptiness of an alternating parity tree automaton can be decided in exponential time.

# Translating ATL<sub>sc</sub> into QCTL



- player A has moves  $m_1^A$ , ...,  $m_n^A$ ;
- from the transition table, we can compute the set Next( $\bigcirc$ , A,  $m_i^A$ ) of states that can be reached from  $\bigcirc$  when player A plays  $m_i^A$ .

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## $\langle A \rangle \varphi$ can be encoded as follows:

$$\exists m_1^A. \exists m_2^A \ldots \exists m_n^A.$$

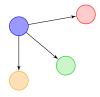
- this corresponds to a strategy:  $\mathbf{A} \mathbf{G}(m_i^A \Leftrightarrow \bigwedge \neg m_j^A)$ ;
- the outcomes all satisfy  $\varphi$ :

$$A[G(q \land m_i^A \Rightarrow X Next(q, A, m_i^A)) \Rightarrow \varphi].$$





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### Corollary

 $ATL_{sc}$  model checking is decidable, with non-elementary complexity (TOWER-complete).

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 $ATL_{sc}^{0}$  (quantification restricted to memoryless strategies) model checking is PSPACE-complete.



# What about satisfiability?

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## Why?



The translation from  $ATL_{sc}$  to QCTL assumes that the game structure is given!

# Satisfiability for turn-based games

## Theorem (LM13b)

When restricted to turn-based games,  $ATL_{sc}$  satisfiability is decidable.

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- player  $\square$  has moves  $\bigcirc$ , and  $\bigcirc$ .
- a strategy can be encoded by marking some of the nodes of the tree with proposition mov<sub>A</sub>.

## $\langle A \rangle \varphi$ can be encoded as follows:

### $\exists \mathsf{mov}_A$ .

- it corresponds to a strategy:  $A G(turn_A \Rightarrow E X_1 mov_A)$ ;
- the outcomes all satisfy  $\varphi$ :  $\mathbf{A}[\mathbf{G}(\mathsf{turn}_A \wedge \mathbf{X} \mathsf{mov}_A) \Rightarrow \varphi]$ .

# What about Strategy Logic? [CHP07,MMV10]

## Strategy logic

Explicit quantification over strategies + strategy assignement

### Example

$$\langle A \rangle \varphi \equiv \exists \sigma_1.\mathsf{assign}(\sigma_1, A).\varphi$$

Strategy logic can also be translated into QCTL.

#### **Theorem**

- Strategy-logic model-checking is decidable.
- Strategy-logic satisfiability is decidable when restricted to turn-based games.

### Conclusions and future works

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- QCTL is a powerful extension of CTL;
- it is equivalent to MSO over finite graphs and regular trees;
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### Future directions

- Defining interesting (expressive yet tractable) fragments of those logics;
- Obtaining practicable algorithms.
- Considering randomised strategies.